

# Python for Science and Engg: SciPy

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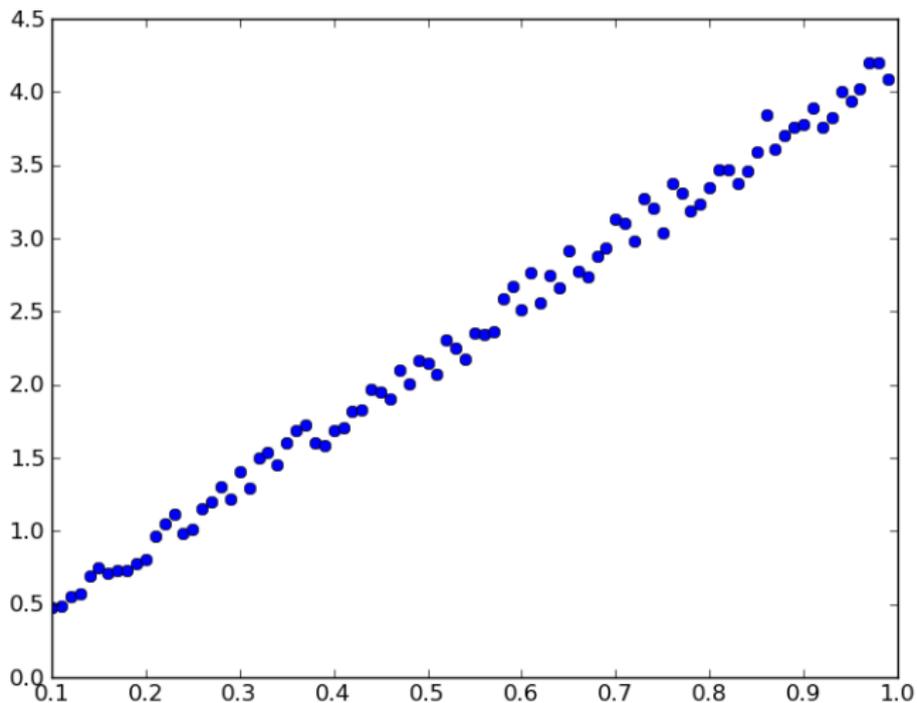
SciPy.in 2010, Tutorials

# Outline

- 1 Least Squares Fit
- 2 Solving linear equations
- 3 Finding Roots
- 4 ODEs
- 5 FFTs

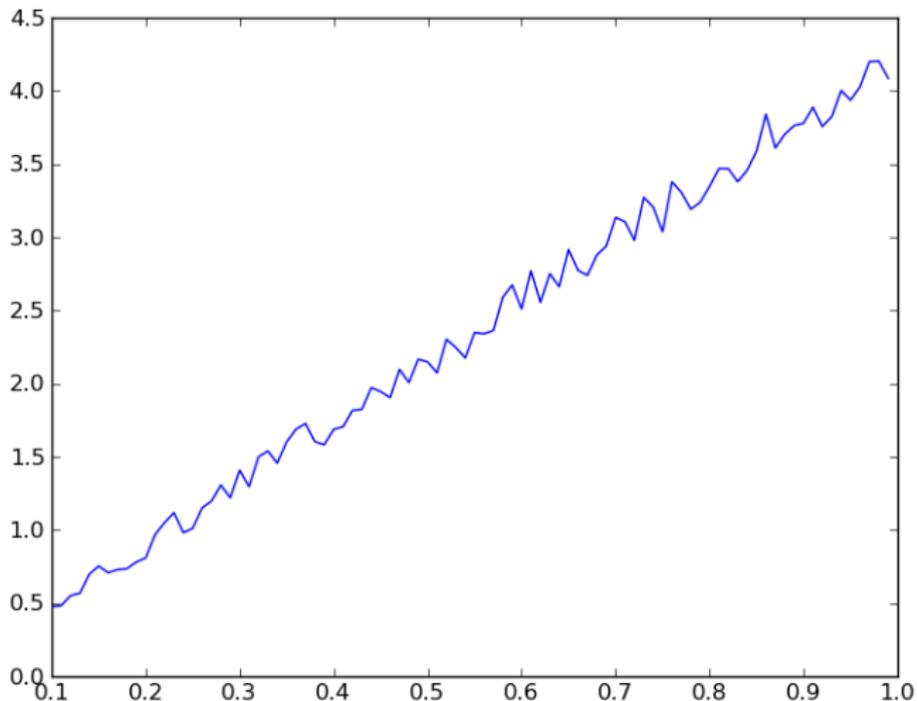
# $L$ vs. $T^2$ - Scatter

Linear trend visible.



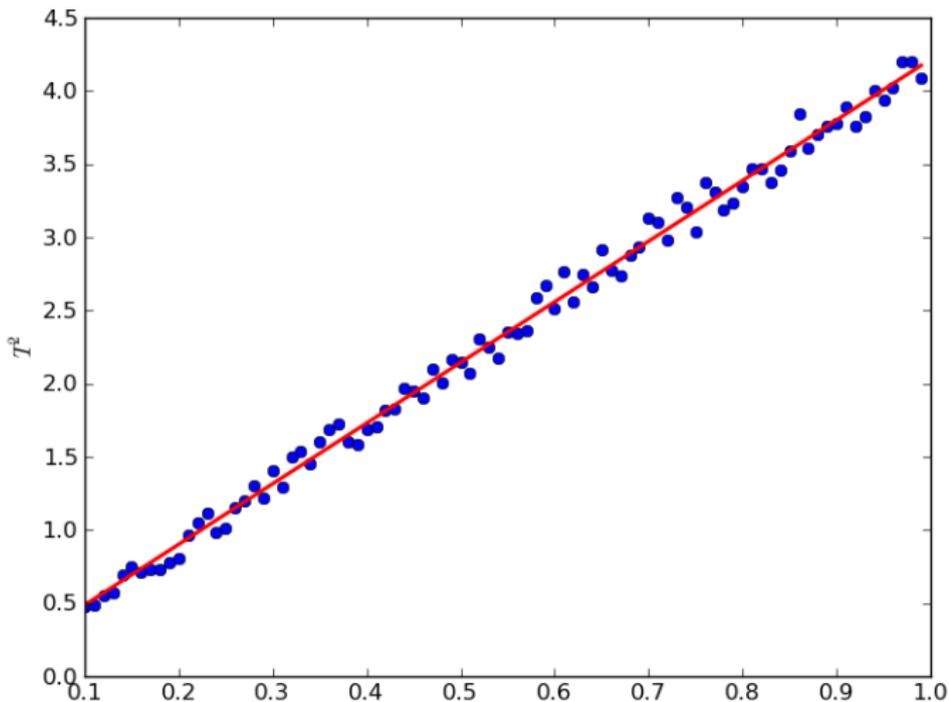
# $L$ vs. $T^2$ - Line

This line does not make any mathematical sense.



# $L$ vs. $T^2$ - Least Square Fit

This is what our intention is.



# Matrix Formulation

- We need to fit a line through points for the equation  $T^2 = m \cdot L + c$
- In matrix form, the equation can be represented as

$$T_{sq} = A \cdot p, \text{ where } T_{sq} \text{ is } \begin{bmatrix} T_1^2 \\ T_2^2 \\ \vdots \\ T_N^2 \end{bmatrix}, \text{ A is } \begin{bmatrix} L_1 & 1 \\ L_2 & 1 \\ \vdots & \vdots \\ L_N & 1 \end{bmatrix} \text{ and}$$

$$p \text{ is } \begin{bmatrix} m \\ c \end{bmatrix}$$

- We need to find  $p$  to plot the line

# Getting $L$ and $T^2$

```
In []: L, T = loadtxt('pendulum.txt',  
                    unpack=True)
```

```
In []: tsq = T*T
```

# Generating A

```
In []: A = array([L, ones_like(L)])  
In []: A = A.T
```

# lstsq...

- Now use the `lstsq` function
- Along with a lot of things, it returns the least squares solution

```
In []: result = lstsq(A,tsq)
```

```
In []: coef = result[0]
```

# Least Square Fit Line ...

We get the points of the line from `coef`

```
In []: Tline = coef[0]*L + coef[1]
```

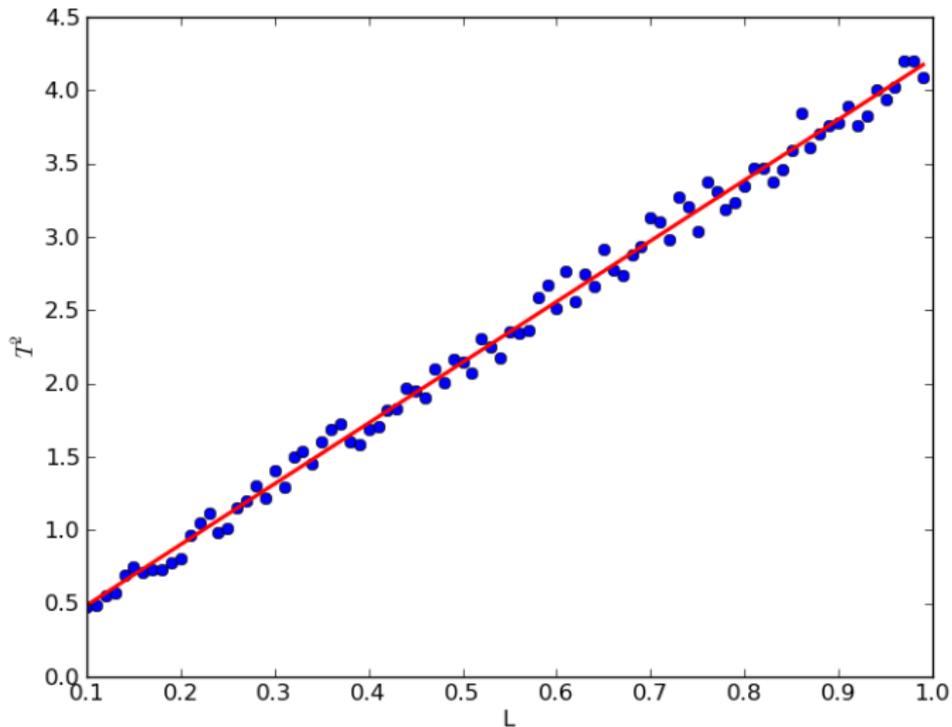
```
In []: Tline.shape
```

- Now plot `Tline` vs. `L`, to get the Least squares fit line.

```
In []: plot(L, Tline, 'r')
```

```
In []: plot(L, tsq, 'o')
```

# Least Squares Fit



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# Solution of equations

Consider,

$$3x + 2y - z = 1$$

$$2x - 2y + 4z = -2$$

$$-x + \frac{1}{2}y - z = 0$$

Solution:

$$x = 1$$

$$y = -2$$

$$z = -2$$

# Solving using Matrices

Let us now look at how to solve this using **matrices**

```
In []: A = array([[3, 2, -1],  
                 [2, -2, 4],  
                 [-1, 0.5, -1]])
```

```
In []: b = array([1, -2, 0])
```

```
In []: x = solve(A, b)
```

# Solution:

```
In []: x
```

```
Out []: array([ 1., -2., -2.])
```

# Let's check!

```
In []: Ax = dot(A, x)
```

```
In []: Ax
```

```
Out []: array([ 1.00000000e+00, -2.00000000e+00,  
-1.11022302e-16])
```

The last term in the matrix is actually 0!

We can use `allclose()` to check.

```
In []: allclose(Ax, b)
```

```
Out []: True
```

10 m

# Problem

Solve the set of equations:

$$x + y + 2z - w = 3$$

$$2x + 5y - z - 9w = -3$$

$$2x + y - z + 3w = -11$$

$$x - 3y + 2z + 7w = -5$$

15 m

# Solution

Use `solve()`

$$x = -5$$

$$y = 2$$

$$z = 3$$

$$w = 0$$

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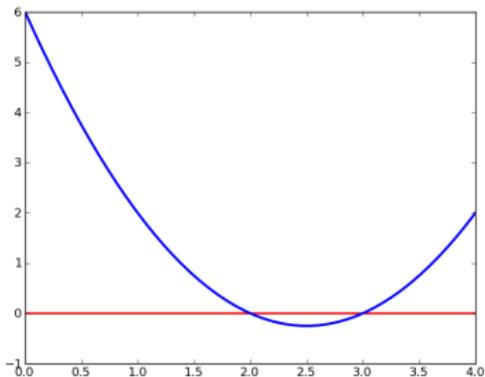
# SciPy: roots

- Calculates the roots of polynomials
- To calculate the roots of  $x^2 - 5x + 6$

```
In []: coeffs = [1, -5, 6]
```

```
In []: roots(coeffs)
```

```
Out []: array([3., 2.])
```



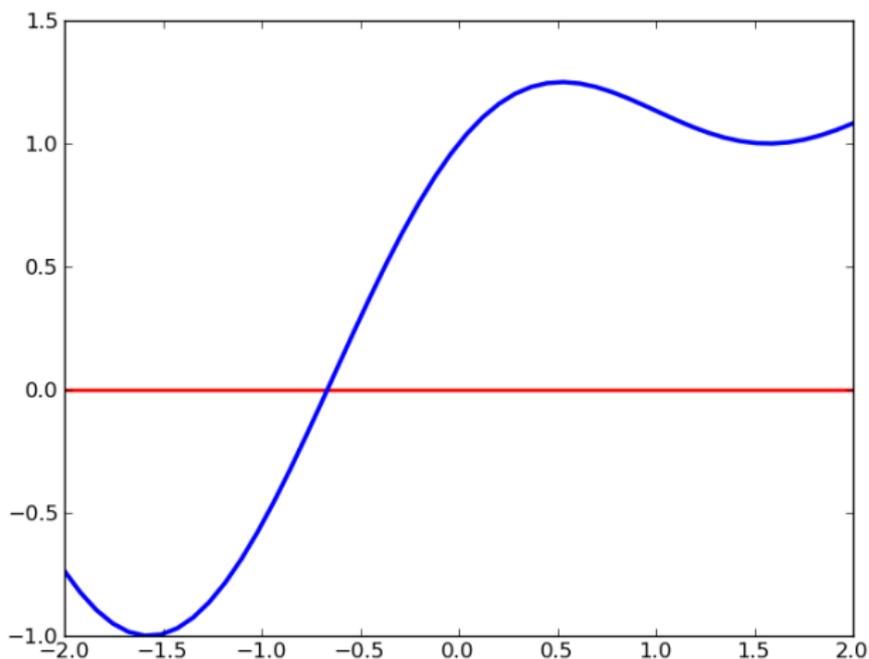
# SciPy: `fsolve`

```
In []: from scipy.optimize import fsolve
```

- Finds the roots of a system of non-linear equations
- Input arguments - Function and initial estimate
- Returns the solution

# fsolve

Find the root of  $\sin(z) + \cos^2(z)$  nearest to 0



# fsolve

Root of  $\sin(z) + \cos^2(z)$  nearest to 0

```
In []: fsolve(sin(z)+cos(z)*cos(z), 0)
NameError: name 'z' is not defined
```

# fsolve

```
In []: z = linspace(-pi, pi)
In []: fsolve(sin(z)+cos(z)*cos(z), 0)
```

**TypeError:**

'numpy.ndarray' object is not callable

# Functions - Definition

We have been using them all along. Now let's see how to define them.

```
In []: def g(z):  
      ....:     return sin(z)+cos(z)*cos(z)
```

- **def** – keyword
- name: **g**
- arguments: **z**
- **return** – keyword

# Functions - Calling them

```
In []: g()
```

```
-----  
TypeError:g() takes exactly 1 argument  
(0 given)
```

```
In []: g(0)
```

```
Out []: 1.0
```

```
In []: g(1)
```

```
Out []: 1.1333975665343254
```

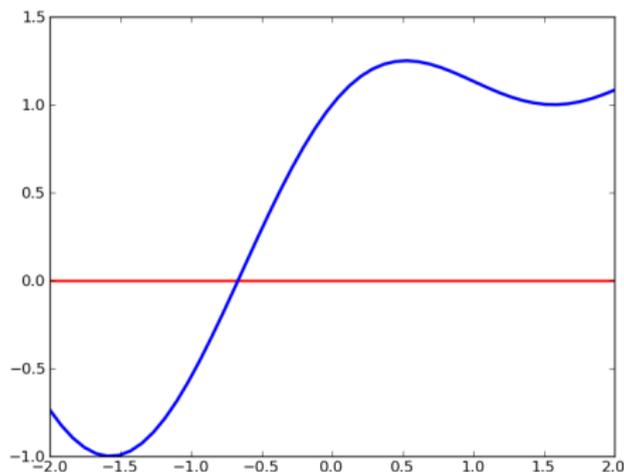
More on Functions later ...

# fsolve ...

Find the root of  $\sin(z) + \cos^2(z)$  nearest to 0

```
In []: fsolve(g, 0)
```

```
Out []: -0.66623943249251527
```

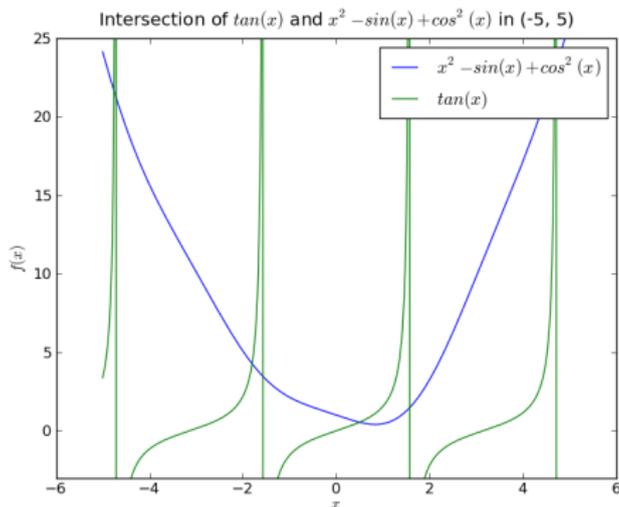


# Exercise Problem

Find the root of the equation  
 $x^2 - \sin(x) + \cos^2(x) = \tan(x)$  nearest to 0

# Solution

```
def g(x):
    return x**2 - sin(x) + cos(x)*cos(x) - tan(x)
fsolve(g, 0)
```



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# Solving ODEs using SciPy

- Consider the spread of an epidemic in a population
- $\frac{dy}{dt} = ky(L - y)$  gives the spread of the disease
- $L$  is the total population.
- Use  $L = 2.5E5, k = 3E - 5, y(0) = 250$
- Define a function as below

```
In []: from scipy.integrate import odeint
In []: def epid(y, t):
.....     k = 3.0e-5
.....     L = 2.5e5
.....     return k*y*(L-y)
.....
```

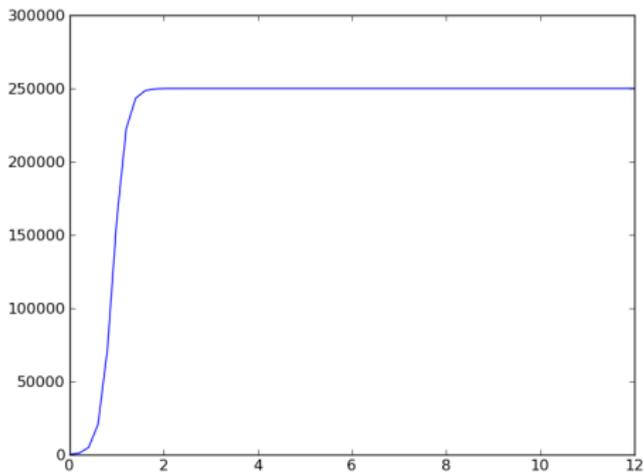
# Solving ODEs using SciPy ...

```
In []: t = linspace(0, 12, 61)
```

```
In []: y = odeint(epid, 250, t)
```

```
In []: plot(t, y)
```

# Result



# ODEs - Simple Pendulum

We shall use the simple ODE of a simple pendulum.

$$\ddot{\theta} = -\frac{g}{L}\sin(\theta)$$

- This equation can be written as a system of two first order ODEs

$$\dot{\theta} = \omega \quad (1)$$

$$\dot{\omega} = -\frac{g}{L}\sin(\theta) \quad (2)$$

At  $t = 0$  :

$$\theta = \theta_0(10^\circ) \quad \& \quad \omega = 0 \quad (\text{Initial values})$$

# ODEs - Simple Pendulum ...

- Use `odeint` to do the integration

```
In []: def pend_int(initial, t):  
.....     theta = initial[0]  
.....     omega = initial[1]  
.....     g = 9.81  
.....     L = 0.2  
.....     F=[omega, -(g/L)*sin(theta)]  
.....     return F  
.....
```

# ODEs - Simple Pendulum ...

- `t` is the time variable
- `initial` has the initial values

```
In []: t = linspace(0, 20, 101)
```

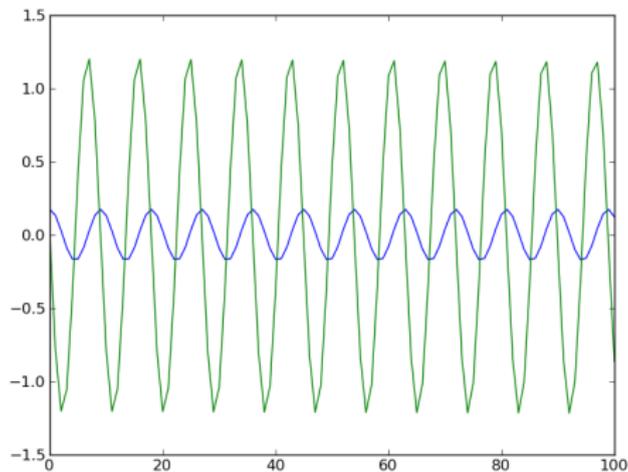
```
In []: initial = [10*2*pi/360, 0]
```

# ODEs - Simple Pendulum ...

```
In []: from scipy.integrate import odeint
```

```
In []: pend_sol = odeint(pend_int,  
                        initial,t)
```

# Result



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# The FFT

- We have a simple signal  $y(t)$
- Find the FFT and plot it

```
In []: t = linspace(0, 2*pi, 500)
```

```
In []: y = sin(4*pi*t)
```

```
In []: f = fft(y)
```

```
In []: freq = fftfreq(500, t[1] - t[0])
```

```
In []: plot(freq[:250], abs(f)[:250])
```

```
In []: grid()
```

# FFTs cont...

```
In []: y1 = ifft(f) # inverse FFT  
In []: allclose(y, y1)  
Out []: True
```

# FFTs cont...

Let us add some noise to the signal

```
In []: yr = y + random(size=500)*0.2
```

```
In []: yn = y + normal(size=500)*0.2
```

```
In []: plot(t, yr)
```

```
In []: figure()
```

```
In []: plot(freq[:250],  
...:      abs(fft(yn))[:250])
```

- **random**: produces uniform deviates in  $[0, 1)$
- **normal**: draws random samples from a Gaussian distribution
- Useful to create a random matrix of any shape

# FFTs cont...

Filter the noisy signal:

```
In []: from scipy import signal
In []: yc = signal.wiener(yn, 5)
In []: clf()
In []: plot(t, yc)
In []: figure()
In []: plot(freq[:250],
...:      abs(fft(yc))[:250])
```

Only scratched the surface here ...

# Things we have learned

- Least Square Fit
- Solving Linear Equations
- Defining Functions
- Finding Roots
- Solving ODEs
- Random number generation
- FFTs and basic signal processing